

Modulating rotary actuator fail-safe and extended functionalities for adjusting dampers in technical building installations

- \bullet Air damper size up to approx. 1.2 m^2
- Torque motor 6 Nm
- Nominal voltage AC/DC 24 V
- Control modulating 2...10 V
- Position feedback 2...10 V
- Running time motor 4 s



Technical data

Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
	Power consumption in operation	11 W	
	Power consumption in rest position	3 W	
	Power consumption for wire sizing	22 VA	
	Power consumption for wire sizing note	Imax 20 A @ 5 ms	
	Connection supply / control	Cable 1 m, 4 x 0.75 mm ²	
	Parallel operation	Yes (note the performance data)	
Functional data	Torque motor	6 Nm	
	Operating range Y	210 V	
	Input impedance	100 kΩ	
	Position feedback U	210 V	
	Position feedback U note	Max. 0.5 mA	
	Setting fail-safe position	0100%, adjustable in increments of 10% (POP rotary knob on 0 corresponds to left end stop)	
	Bridging time (PF)	0 s	
	Position accuracy	±5%	
	Direction of motion motor	selectable with switch 0/1	
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)	
	Direction of motion fail-safe	selectable with switch 0100%	
	Manual override	with push-button	
	Angle of rotation	Max. 95°	
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops	
	Minimum angle of rotation	Min. 30°	
	Running time motor	4 s / 90°	
	Running time fail-safe	4 s / 90°	
	Adaptation setting range	manual (automatic on first power-up)	
	Sound power level, motor	60 dB(A)	
	Sound power level, fail-safe	60 dB(A)	
	Mechanical interface	Universal shaft clamp 826.7 mm	
	Position indication	Mechanical, pluggable	
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)	
	Power source UL	Class 2 Supply	
	Degree of protection IEC/EN	IP54	
	Degree of protection NEMA/UL	NEMA 2	
	Enclosure	UL Enclosure Type 2	



afety data	EMC	CE according to 2014/30/EU	
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1	
		The UL marking on the actuator depends on the production site, the device is UL-compliant	
		in any case	
	Type of action	Type 1.AA	
	Rated impulse voltage supply / control	0.8 kV	
	Pollution degree 3		
	Ambient humidity	Max. 95% RH, non-condensing	
	Ambient temperature	-3050°C [-22122°F]	
	Storage temperature	-4080°C [-40176°F]	
	Servicing	maintenance-free	
Weight	Weight	1.1 kg	
Terms	Abbreviations	POP = Power off position / fail-safe position PF = Power fail delay time / bridging time	

Safety notes

	Ŵ	 This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport. Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time. Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation. The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user. Cables must not be removed from the device. To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation and the ventilation conditions must be observed. Self adaptation is necessary when the system is commissioned and after each adjustment of the angle of rotation (press the adaptation push-button once). The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.
Product features		
	Mode of operation	The actuator moves the damper to the desired operating position at the same time as the integrated capacitors are charged. Interrupting the supply voltage causes the damper to be rotated back into the fail-safe position by means of stored electrical energy.

The actuator is connected with a standard control signal of 0...10 V and drives to the position defined by the control signal. Measuring voltage U serves for the electrical display of the damper position 0...100% and as a control signal for other actuators.



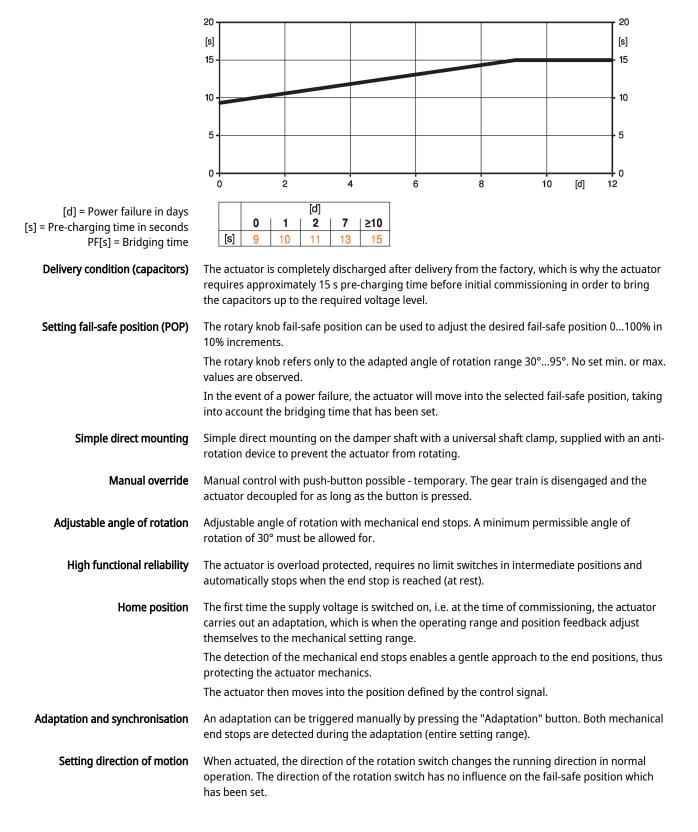
Pre-charging time (start up)

The capacitor actuators require a pre-charging time. This time is used for charging the capacitors up to a usable voltage level. This ensures that, in the event of a power failure, the actuator can move at any time from its current position into the preset fail-safe position.

The duration of the pre-charging time depends mainly on following factors:

- Duration of the power failure
- PF delay time (bridging time)

Typical pre-charging times







Electrical accessories	Description	Туре
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 500 Ω add-on	P500A
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 2.8 k Ω add-on	P2800A
	Feedback potentiometer 5 k Ω add-on	P5000A
	Feedback potentiometer 10 k Ω add-on	P10000A
	Adapter for auxiliary switch and feedback potentiometer	Z-SPA
	Signal converter voltage/current 100 k Ω 420 mA, Supply AC/DC 24 V	Z-UIC
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
Mechanical accessories	Description	Туре
	Actuator arm for standard shaft clamp (one-sided)	AH-25
	Shaft extension 240 mm Ø20 mm for damper shaft Ø 822.7 mm	AV8-25
	Mounting kit for linkage operation for flat installation	ZG-NMA
	* Adapter Z-SPA	
	It is imperative that this adapter will be ordered if an auxiliary switch or a potentiometer is required.	a feedback

Electrical installation



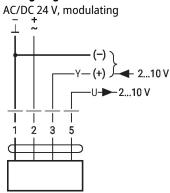
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

Wire colours:

- 1 = black
- 2 = red
- 3 = white
- 5 = orange

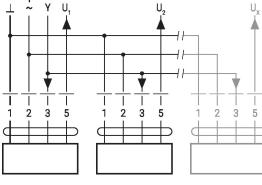
Wiring diagrams



1	2	3		
_~	٢	2 V	3	5
	7	10 V	5	$\mathbf{\mathcal{I}}$

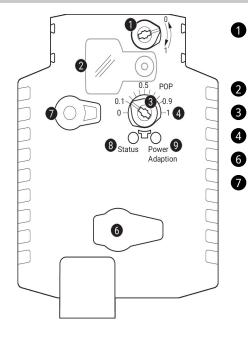


Parallel operation $\overline{\perp} \stackrel{+}{\sim} Y U_{\uparrow}$



• Max. 8 actuators in parallel • Parallel operation is permitted only on non-connected axes • Do not fail to observe performance data with parallel operation

Operating controls and indicators



1 Direction of rotation switch

Switch over:
Cover, POP button
POP button

- 4 Scale for manual adjustment
- (no function) 6
 - Manual override button

Press button: Release button:

Gear train disengages, motor stops, manual override possible Gear train engages, standard mode

Direction of rotation changes

LED displays

yellow 8	green 🥑	Meaning / function	
Off	On	Operation OK	
Off	Flashing	POP function active	
On	Off	Fault	
Off	Off	Not in operation	
On	On	Adaptation process active	

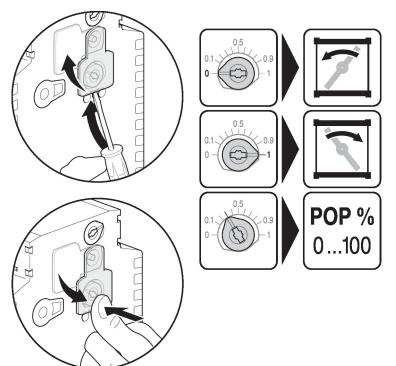


9 Push-button (LED green)

Press button: Triggers angle of rotation adaptation, followed by standard mode



Setting emergency setting position (POP)



Dimensions

Spindle length

	Min. 42
	Min. 20

Clamping range

	<u>O</u> I		\mathbf{x}
	826.7	≥8	≤26.7
*	820	≥8	≤20

*Option: Shaft clamp mounted below: If an auxiliary switch or a feedback potentiometer is used the adapter Z-SPA is required.

