

Communicative damper actuator for adjusting dampers in technical building installations

- Air damper size up to approx. 4 m²
- Torque motor 20 Nm
- Nominal voltage AC/DC 24 V
- Control modulating, communicative 2...10 V variable
- Position feedback 2...10 V variable
- Communication via Belimo MP-Bus
- Conversion of sensor signals

Technical data



Technical data sheet

Electrical data	Nominal voltage	AC/DC 24 V	
	Nominal voltage frequency	50/60 Hz	
	Nominal voltage range	AC 19.228.8 V / DC 21.628.8 V	
	Power consumption in operation	3.5 W	
	Power consumption in rest position	1.4 W	
	Power consumption for wire sizing	6 VA	
	Connection supply / control	Cable 1 m, 4 x 0.75 mm ²	
	Parallel operation	Yes (note the performance data)	
Data bus communication	Communicative control	MP-Bus	
	Number of nodes	MP-Bus max. 8	
Functional data	Torque motor	20 Nm	
	Torque variable	25%, 50%, 75% reduced	
	Operating range Y	210 V	
	Input impedance	100 kΩ	
	Operating range Y variable	Start point 0.530 V	
		End point 2.532 V	
	Operating modes optional	Open/close	
		3-point (AC only)	
	Position feedback U	Modulating (DC 032 V) 210 V	
	Position feedback U note	Max. 0.5 mA	
	Position feedback U variable		
	Position reedback o variable	Start point 0.58 V End point 2.510 V	
	Position accuracy	±5%	
	Direction of motion motor	selectable with switch 0/1	
	Direction of motion note	Y = 0 V: At switch position 0 (ccw rotation) / 1 (cw rotation)	
	Direction of motion variable	electronically reversible	
	Manual override	with push-button, can be locked	
	Angle of rotation	Max. 95°	
	Angle of rotation note	can be limited on both sides with adjustable mechanical end stops	
	Running time motor	150 s / 90°	
	Running time motor variable	86346 s	
	Adaptation setting range	manual	
	Adaptation setting range variable	No action	
		Adaptation when switched on Adaptation after pushing the manual override button	

SM24A-MP

MP/27BUS



Functional data	Override control	MAX (maximum position) = 100% MIN (minimum position) = 0% ZS (intermediate position, AC only) = 50%	
	Override control variable	MAX = (MIN + 32%)100% MIN = 0%(MAX – 32%) ZS = MINMAX	
	Sound power level, motor	45 dB(A)	
	Mechanical interface	Universal shaft clamp reversible 1020 mm	
	Position indication	Mechanical, pluggable	
Safety data	Protection class IEC/EN	III, Safety Extra-Low Voltage (SELV)	
	Power source UL	Class 2 Supply	
	Degree of protection IEC/EN	IP54	
	Degree of protection NEMA/UL	NEMA 2	
	Enclosure	UL Enclosure Type 2	
	EMC	CE according to 2014/30/EU	
	Certification IEC/EN	IEC/EN 60730-1 and IEC/EN 60730-2-14	
	UL Approval	cULus according to UL60730-1A, UL60730-2-14 and CAN/CSA E60730-1	
		The UL marking on the actuator depends on the production site, the device is UL-compliant in any case	
	Type of action	Type 1	
	Rated impulse voltage supply / control	0.8 kV	
	Pollution degree	3	
	Ambient humidity	Max. 95% RH, non-condensing	
	Ambient temperature -3050°C [-22122°F]		
	Storage temperature	-4080°C [-40176°F]	
	Servicing	maintenance-free	
Weight	Weight	1.1 kg	

Safety notes



- This device has been designed for use in stationary heating, ventilation and air-conditioning systems and must not be used outside the specified field of application, especially in aircraft or in any other airborne means of transport.
- Outdoor application: only possible in case that no (sea) water, snow, ice, insolation or aggressive gases interfere directly with the device and that it is ensured that the ambient conditions remain within the thresholds according to the data sheet at any time.
- Only authorised specialists may carry out installation. All applicable legal or institutional installation regulations must be complied during installation.
- The device may only be opened at the manufacturer's site. It does not contain any parts that can be replaced or repaired by the user.
- Cables must not be removed from the device.
- To calculate the torque required, the specifications supplied by the damper manufacturers concerning the cross-section, the design, the installation situation and the ventilation conditions must be observed.
- The device contains electrical and electronic components and must not be disposed of as household refuse. All locally valid regulations and requirements must be observed.



Mode of operation	n Conventional operation:		
	The actuator is connected with a standard control signal of 010 V and drives to the positi defined by the control signal. The measuring voltage U serves for the electrical display of t actuator position 0.5100% and as control signal for other actuators.		
	Operation on Bus:		
	The actuator receives its digital control signal from the higher level controller via the MP-Bus and drives to the position defined. Connection U serves as communication interface and does not supply an analogue measuring voltage.		
Converter for sensors	Connection option for a sensor (passive or active sensor or switching contact). The MP actuator serves as an analogue/digital converter for the transmission of the sensor signal via MP-Bus to the higher level system.		
Parametrisable actuators	The factory settings cover the most common applications. Single parameters can be modified with the Belimo Service Tools MFT-P or ZTH EU.		
Simple direct mounting	Simple direct mounting on the damper shaft with a universal shaft clamp, supplied with an anti- rotation device to prevent the actuator from rotating.		
Manual override	Manual override with push-button possible (the gear train is disengaged for as long as the button is pressed or remains locked).		
Adjustable angle of rotation	Adjustable angle of rotation with mechanical end stops.		
High functional reliability	The actuator is overload protected, requires no limit switches and automatically stops when the end stop is reached.		
Home position	The first time the supply voltage is switched on, i.e. at the time of commissioning, the actuator carries out a synchronisation. The synchronisation is in the home position (0%).		
	The actuator then moves into the position defined by the control signal.		
	$(\mathbf{V}_{1}^{0}) = \mathbf{V} \mathbf{C} \mathbf{W} \mathbf{V}_{1}^{0} = \mathbf{V} \mathbf{V} \mathbf{V} \mathbf{V}_{1}^{0} = \mathbf{V} \mathbf{V} $		
Adaptation and synchronisation	An adaptation can be triggered manually by pressing the "Adaptation" button or with the PC- Tool. Both mechanical end stops are detected during the adaptation (entire setting range).		
	Automatic synchronisation after pressing the manual override button is configured. The synchronisation is in the home position (0%).		
	The actuator then moves into the position defined by the control signal.		
	A range of settings can be adapted using the PC-Tool (see MFT-P documentation)		
es			

Accessories

Gateways	Description	Туре
	Gateway MP to BACnet MS/TP	UK24BAC
	Gateway MP to Modbus RTU	UK24MOD



SM24A-MP

Electrical accessories	Description	Туре
	Auxiliary switch 1 x SPDT add-on	S1A
	Auxiliary switch 2 x SPDT add-on	S2A
	Feedback potentiometer 140 Ω add-on	P140A
	Feedback potentiometer 200 Ω add-on	P200A
	Feedback potentiometer 500 Ω add-on	P500A
	Feedback potentiometer 1 kΩ add-on	P1000A
	Feedback potentiometer 2.8 kΩ add-on	P2800A
	Feedback potentiometer 5 kΩ add-on	P5000A
	Feedback potentiometer 10 kΩ add-on	P10000A
	Signal converter voltage/current 100 kΩ 420 mA, Supply AC/DC 24 V	Z-UIC
	Positioner for wall mounting	SGA24
	Positioner for built-in mounting	SGE24
	Positioner for front-panel mounting	SGF24
	Positioner for wall mounting	CRP24-B1
	MP-Bus power supply for MP actuators	ZN230-24MP
Mechanical accessories	Description	Туре
	Actuator arm for standard shaft clamp (reversible)	AH-20
	Shaft extension 240 mm ø20 mm for damper shaft ø1221 mm CrNi	AV12-25-I
	Shaft extension 240 mm ø20 mm for damper shaft ø822.7 mm	AV8-25
	Ball joint suitable for damper crank arm KH8, Multipack 10 pcs.	KG8
	Ball joint suitable for damper crank arm KH8 / KH10, Multipack 10 pcs.	KG10A
	Damper crank arm Slot width 8.2 mm, clamping range ø1018 mm	KH8
	Shaft clamp one-sided, clamping range ø826 mm, Multipack 20 pcs.	K-ENSA
	Shaft clamp one-sided, clamping range ø1226 mm, for CrNi shaft	K-ENSA-I
	(INOX), Multipack 20 pcs.	
	Shaft clamp reversible, clamping range ø1020 mm	K-SA
	Anti-rotation mechanism 180 mm, Multipack 20 pcs.	Z-ARS180
	Anti-rotation mechanism 230 mm, Multipack 20 pcs.	Z-ARS230
	Form fit insert 10x10 mm, Multipack 20 pcs.	ZF10-NSA
	Form fit insert 12x12 mm, Multipack 20 pcs.	ZF12-NSA
	Form fit insert 15x15 mm, Multipack 20 pcs.	ZF15-NSA
	Form fit insert 16x16 mm, Multipack 20 pcs.	ZF16-NSA
	Mounting kit for linkage operation for flat installation	ZG-SMA
	Position indicator, Multipack 20 pcs.	Z-PI
	Base plate extension for SMA to SM/AM/SMD24R	Z-SMA
Tools	Description	Туре
	Service Tool, with ZIP-USB function, for parametrisable and	ZTH EU
	communicative Belimo actuators, VAV controller and HVAC performance	
	devices	
	Belimo PC-Tool, Software for adjustments and diagnostics	MFT-P
	Adapter for Service-Tool ZTH	MFT-C
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: 6-pin for connection to	ZK1-GEN
	service socket	LAT GEN
	Connecting cable 5 m, A: RJ11 6/4 ZTH EU, B: free wire end for connection	ZK2-GEN
	to MP/PP terminal	

Electrical installation



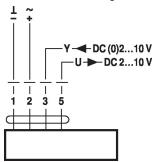
Supply from isolating transformer.

Parallel connection of other actuators possible. Observe the performance data.

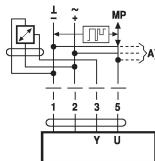


Wiring diagrams

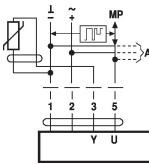
AC/DC 24 V, modulating



Connection of active sensors



Connection of passive sensors



Ni1000	–28+98°C	8501600 Ω ²⁾
PT1000	–35+155°C	8501600 Ω ²⁾
NTC	–10+160°C ¹⁾	200 Ω60 kΩ ²⁾

A) additional MP-Bus nodes (max. 8)

- Supply AC/DC 24 VOutput signal DC 0...10 V
- (max. DC 0...32 V)
- Resolution 30 mV

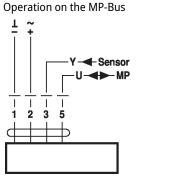
Cable colours:

1 = black

3 = white

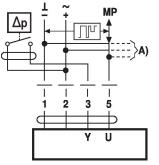
5 = orange

2 = red



5 = orange

Connection of external switching contact



A) additional MP-Bus nodes (max. 8) • Switching current 16 mA @ 24 V

Cable colours:

1 = black

3 = white

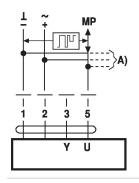
2 = red

• Start point of the operating range must be parametrised on the MP actuator as $\geq 0.5 \text{ V}$

A) additional MP-Bus nodes (max. 8)
1) Depending on the type
2) Resolution 1 Ohm
Compensation of the measured value is recommended

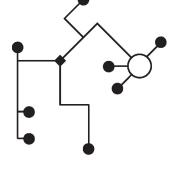
Functions

Functions when operated on MP-Bus Connection on the MP-Bus



A) additional MP-Bus nodes (max. 8)

MP-Bus Network topology



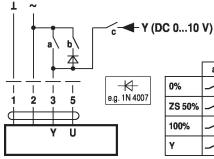
There are no restrictions for the network topology (star, ring, tree or mixed forms are permitted). Supply and communication in one and the same 3-wire cable

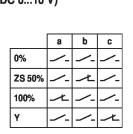
- no shielding or twisting
- necessary • no terminating resistors
- required



Functions with basic values (conventional mode)

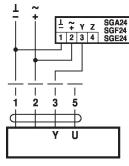
Override control with AC 24 V with relay contacts

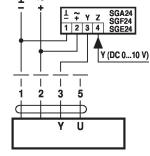




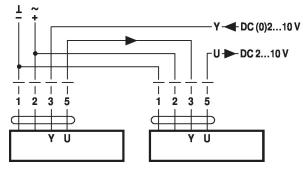
Minimum limit with positioner SG..

Control remotely 0...100% with positioner SG..

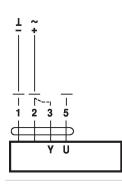




Follow-up control (position-dependent)

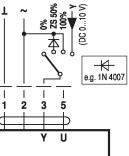


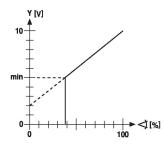
Functional check



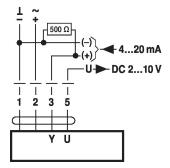
Procedure

Override control with AC 24 V with rotary switch





Control with 4...20 mA via external resistor



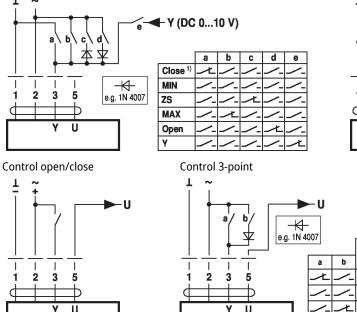
Caution:

The operating range must be set to DC 2...10 V. The 500 Ω resistor converts the 4...20 mA current signal to a voltage signal DC 2...10 V



Functions with specific parameters (parametrisation necessary)

Override control and limiting with AC 24 V with relay contacts



T Close MIN ZS MAX Open (DC 0... <u>क</u>ुरू 0 +e.g. 1N 4007 Т 1 1 2 3 5 C h U

Override control and limiting with AC 24 V with rotary switch

1) **Caution:** This function is only guaranteed if the start point of the operating range is defined as min. 0.5 V.

Operating controls and indicators

	Direction of rotation	on switch
	Switch over:	Direction of rotation changes
$\begin{array}{c} \text{Adaption} \rightarrow \bigcirc 2 \\ \text{Power} & \square \\ \text{Address} \rightarrow \bigcirc 3 \\ \end{array}$	Push-button and L	ED display green
Status	Off: No po	ower supply or malfunction
	On: In op	eration
	Press Trigg button:	ers angle of rotation adaptation, followed by standard mode
	Push-button and L	ED display yellow
	Off:	Standard mode
	On:	Adaptation or synchronisation process active
	Flickering:	MP-Bus communication active
	Flashing:	Request for addressing from MP client
	Press button:	Confirmation of the addressing

4

4 Manual override button

Press button:Gear train disengages, motor stops, manual override possibleReleaseGear train engages, synchronisation starts, followed by standardbutton:mode

5 Service plug

For connecting parametrisation and service tools

Check power supply connection

2 Off and 3 On

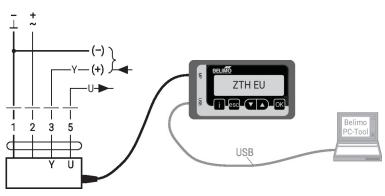
Possible wiring error in power supply



Toola

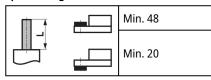
Tools connectionThe actuator can be parametrised by ZTH EU via the service socket.For an extended parametrisation the PC tool can be connected.

Connection ZTH EU / PC-Tool



Dimensions

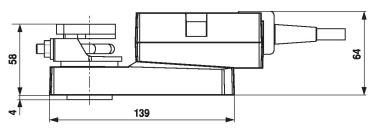
Spindle length

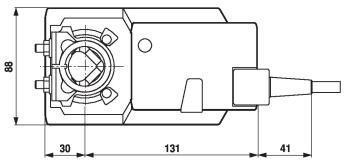


When using a round shaft made of CrNi

Clamping range

	OÌ		\mathbf{x}
	1020	≥10	≤20
CrNi (INOX)	1220	≥10	≤20





Further documentation

(INOX): ø12...20 mm

- Overview MP Cooperation Partners
- Tool connections
- Introduction to MP-Bus Technology

Application notes

• For digital control of actuators in VAV applications patent EP 3163399 must be considered.